

SX arithmetic routines

Introduction

This application note presents programming techniques for performing commonly found arithmetic operations, such as multi-byte binary addition and subtraction, multi-digit BCD addition and subtraction, multiplication and division.

How the program works

1.0 Binary addition and subtraction

The default configuration of SX is to ignore the carry flag in additions and subtractions even the results of those operations do affect that flag. For multi-byte arithmetic operations, it is often desirable to the result of lower bytes to propagate to higher bytes by the means of the carry flag.

To enable the effect of the carry flag, *carryx* must be included in the list of device directives which are specified before the instructions, to make the carry flag an input to add, sub instruction.

The carry flag should be set to zero first before any addition

The SX SUB instruction will set the carry flag to zero if there is an underflow. Therefore, it is necessary for us to set it to one before any subtraction is performed.

The following program segment illustrates 32 bit binary addition. The 4 byte operand1 and the 4 byte operand2 are added together. The result is put back into operand2.

Note that operand1 is located at locations 8,9,a,b, hence 10xx binary and operand2 is at locations c,d,e,f or 11xx binary. Therefore toggling bit 2 of the FSR register effectively enable us to switch back and forth among the two operands. With that in mind, the indirect addressing of SX help us a lot in saving code by just using IND as the register pointed to by FSR.

This routine assumes that the two operands are adjacent to one another and operand1 starts at the 08 location. To relocate the operands to other locations, make sure that they are still adjacent to one another, thus occupying a contiguous 8 bytes, and that operand1 is

aligned to x0 or x8. The only change needed in the code will be the ending condition. Note that in the example, we tested bit 4 which will be toggled after the **inc fsr** instruction if fsr was \$f, and therefore pointing to the last byte. To make the routine work with operands located in \$10-\$17, for example, would need the ending condition be changed from **sb fsr.4** to **sb fsr.3** since the **inc fsr** instruction will change the address of last byte from \$17 to \$18 (%00011000) and set bit 3. Using this technique, we can save the need to store the count separately in order to keep track of the number of bytes added.

	;32 bit addition ;entry = 32 bit operand1 and 32 bit operand2 in binary form ;exit = operand2 become operand1+operand2, carry flag=1 for overflow from MSI		
add32	clc mov	fsr,#operand1	; clear carry, prepare for addition ; points to operand 1 first
add_more	clrb mov setb add inc sb jmp ret	fsr.2 w,ind fsr.2 ind,w fsr fsr.4 add_more	; toggle back to operand 1 ; get contents into the work register ; points to operand 2 ; operand2=operand2+operand1 ; next byte ; done? (fsr=\$10?) ; not yet ; done, return to calling routine

The 32 bit subtraction routine is very similar to addition, except that we set the carry flag first to indicate no underflow. Note that the result is in operand2 and it is operand2-operand1, not the other way around. When the carry flag is 0 on return, it means that the result is negative and is therefore in 2's complement form.

	;32 bit subtraction ;entry = 32 bit operand1 and 32 bit operand2 in binary form ;exit = operand2 become operand2-operand1, carry flag=0 for underflow from MSB		
sub32	stc		; set carry, prepare for subtraction
	mov	fsr,#operand1	; points to operand 1 first
sub_more	clrb	fsr.2	; toggle back to operand 1
	mov	w,ind	; get contents into the work register
	setb	fsr.2	; points to operand 2
	sub	ind,w	; operand2=operand2-operand1
	inc	fsr	; next byte
	sb	fsr.4	; done? (fsr=\$10?)
	jmp	sub more	; not yet
	ret	—	; done, return to calling routine

2.0 BCD addition and subtraction

The next topic will be BCD addition. In a lot of application where calculation result needs to be displayed, BCD or binary coded decimal can be much more easily converted into visual form, as in the case of adding machine or calculator.

The algorithm here for BCD addition is very similar to binary addition except for 1 important difference: decimal adjustment or correction. The need for such operation will be evident as we examine the follow simple addition:

85 + 15 = 9A

Obviously the correction result should be 100 in BCD. We can see that by adding 6 to the least significant digit (LSD), in this case, \$9A+6=\$A0, will correct the LSD. Finally, by adding a \$60 to the whole number (equal to adding 6 to the most significant digit, MSD), the entire number is corrected to \$00 with a carry of 1, which can be propagated into the next byte.

By looking at another example: 19+19=32. After the addition, the digit carry will be set to one, indicating an overflow in the LSD. The result then can be corrected by adding 6 to the LSD, giving us the correct answer of 38.

In general, we will do a correction on LSD of the result if the digit carry is set or the LSD is greater than 9. The same is true for the MSD. It will be corrected, i.e., added with 6, when the carry bit is set or the MSD is greater than 9.

The tricky part now is how to check if the digit is greater than 9. A straight implementation will require masking 1 nibble off at a time and do a subtraction. This will require additional storage if we do not want the operands (and the result) to be changed. The way it is implemented here is a bitwise comparison.

Let us look at a 4 bit number, if bit number 3 is 0, the number must be then %0xxx, and therefore ranges from 0-7, hence less than 9. If that's not the case, then we go on to check bit 2. If it is a one, then we have %11xx, and the number is definitely bigger than 9, since the minimum is already %1100 or 12. If bit 2 is a zero, we proceed to check bit 1. If this bit is a zero, then we have %100x, which means the number is either 8 or 9, and no correction is needed. But if bit 1 is an one, then we have %101x, which is higer than 9 and correction will be needed.

This method of detecting whether the digit is greater than 9 or not, is used twice in the code. Once for LSD and once for MSD. The changes is only the bit number that is being checked on.

One more point worth noting is the carry bit. After the initial binary addition, we have to store the carry bit that is used to propagate the result to higher bytes. The reason for doing this is simple: the decimal correction process of adding 6 to the number will clear the carry bit.

Notice also that the ending condition has been changed to **sb fsr.2** instead of **sb fsr.4**. This is simply because the code happens to point at operand 1 at that time and it just saves us code to check if fsr is pointing to the last byte of operand 1 at location 00 (% 1011) or not. The fsr will be 0 (% 1100) after the increment operation and therefore setting bit 2.

	;entry = 8 BCD digit operand1 and 8 BCD digit operand2 in BCD form ;exit = operand2 become operand2+operand1, carry flag=1 for overflow from MSB ; operand1 will be DESTROYED		
badd32	clc mov fsr,#operand1	; clear carry, prepare for addition ; points to operand 1 first	
badd_more			
	mov w,ind clr ind	; get contents into the working register	
	setb fsr.2	; points to operand 2	
	add ind,w	; operand2=operand2+operand1	
	clrb fsr.2 rl ind	; store carry bit which will be altered by decimal	
		; adjustment (adding 6)	
	setb fsr.2	; points back to operand 2	
	snb status.1 jmp dcor	; digit carry set? if so, need decimal correction	
	jnb ind.3,ck_overflow	; if 0xxx, check MSD	
	jb ind.2,dcor	; if 11xx, it's >9, thus need correction	
	jnb ind.1,ck_overflow	; 100x, number is 8 or 9, no decimal correction	
	; here if 101x, decimal adjust		
dcor	clc	; clear effect of previous carry	
	add ind,#6	; decimal correction by adding 6	
	; finish dealing with least sigr		
ck_overflow	clrb fsr.2 jb ind.0,dcor_msd	; points to operand1 ; stored carry=1, decimal correct	
	; test if MSD > 9	, stored carry=1, decimal correct	
	setb fsr.2	; points back to operand2	
	jnb ind.7,next_badd		
	jb ind.6,dcor_msd jnb ind.5,next_badd	; if 11xx, it's >9, thus need correction ; if 100x, it's <9	
	-	,,	
dcor_msd	;here if 101x, decimal adjust clc	; clear effect of carry	
ucoi_iiisu	setb fsr.2	; make sure that it's pointing at the result	
	add ind,#\$60	; decimal correct	
next_badd	clrb fsr.2	; points to stored carry	
	snb ind.0	; skip if not set	
	stc	; restore stored carry	
	inc fsr sb fsr.2	; next byte ; done? (fsr=\$0c?)	
	jmp badd_more	; not yet	
	ret	; done, return to calling routine	

BCD subtraction is very similar to addition except for a few notes, which are summarized below:

1. carry flag is set first before subtraction which means no borrow;

2. decimal correction is done when:

- a. digit carry is 0;
- b. least significant digit (LSD) is greater than 9;
- c. carry is 0;
- d. most significant digit (MSD) is greater than 9;

3. when the result is negative, it is not suitable for display, e.g., on 7 segment LEDs. Therefore, an operation which negates the number is performed by 0-result. This will enable us to obtain the magnitude of the number. The no carry condition will keep us reminded of the fact that it is a negative number. This situation is also occurring in a binary subtraction, whereas a no carry condition means the result is in 2's complement form. This is fine since the 2's complement is not used for display and it is useful for further computation.

bsub32	;entry ;exit = ; call snc jmp call call		and 8 BCD digit operand2 in BCD form rand2-operand1, carry flag=0 for underflow from MSB carry flag=1 for positive result TROYED ; do subtraction ; no carry=underflow? ; carry=1 positive, done ; yes, get the magnitude, 0-result ; keep in mind that this result is a negative ; number (carry=0)
bs_done	ret		
bs32 bsub_more	stc mov clr setb setb sub clrb rl setb sb jmp	fsr,#operand1 w,ind ind ind.7 fsr.2 ind,w fsr.2 ind fsr.2 status.1 dec_cor	 ; set carry, prepare for subtraction ; points to operand 1 first ; get contents into the working register ; set to 1 so that carry=1 after rl instruction ; points to operand 2 ; operand2=operand2+operand1 ; store carry bit which will be altered by decimal ; adjustment (adding 6) ; points back to operand 2 ; digit carry set? if so, need decimal correction
	jnb jb jnb	ind.3,ck_underflow ind.2,dec_cor ind.1,ck_underflow	; if 0xxx, check MSD ; if 11xx, it's >9, thus need correction ; 100x, number is 8 or 9, no decimal correction
	; here	if 101x, decimal adjust	
dec_corstc	sub		effect of previous carry ; decimal correction by subtracting 6

ck_underflow	clrb jnb	fsr.2 ind.0,dadj_msd MSD > 9 fsr.2	icant digit, proceed to MSD ; points to operand1 ; stored carry=0, decimal adjust ; points back to operand2 ; if 0xxx, it's <9, add next byte ; if 11xx, it's >9, thus need correction ; if 100x, it's <9
dadj_msd	;here i stc setb sub	f 101x, decimal adjust fsr.2 ind,#\$60	; clear effect of carry ; make sure that it's pointing at the result ; decimal correct
next_bsub	clrb sb clc inc sb jmp ret	fsr.2 ind.0 fsr fsr.2 bsub_more	; points to stored carry ; skip if not set ; restore stored carry ; next byte ; done? (fsr=\$0c?) ; not yet ; done, return to calling routine
neg_result mov_more	; the in		and change operand2 to 0 esult or getting the magnitude of a is in complement form ; points to ; operand2 ; temp. storage ; clear operand2 ; points to operand1 ; store result ; next byte ; done? ; no ; yes, finish

3.0 Binary to BCD conversion

In a lot of situations, we will find BCD representations very difficult to deal with, especially when anything more than addition and subtraction is needed, due to the need for decimal correction. This problem is alleviated by representing the numbers internally as binary to facilitate computation and convert it to BCD for display or printing purposes. In this section, we will discuss how that is implemented.

There are many different algorithms for binary to BCD conversions. We will only consider one of the easiest to implement, that is, shifting the binary number to the left and let the most significant bit be shifted into a BCD result. The result is then continuously decimally corrected to give a right answer.

In the following code segment, we have implemented a 32 bit binary number to 10 digit BCD conversion routine. With the RL instruction of the SX, the shift operation of both numbers together is a breeze.

Decimal correction is done here differently than before. Instead of checking the carry and digit carry, we check the BCD value before a shift and adjust it properly. This will save us both code and time. This was not possible before in our addition and subtraction routines since we were not doing shift operations.

Current value	binary	Shifted value in binary	Shifted value in hex	What the shifted value should be in BCD
0	0000	0000	0	0
1	0001	0010	2	2
2	0010	0100	4	4
3	0011	0110	6	6
4	0100	1000	8	8
5	0101	1010	A	10
6	0110	1100	С	12
7	0111	1110	E	14
8	1000	1 0000	10	16
9	1001	1 0010	12	18

To see how this is done, let's look at some examples:

From the table, we can see that whenever the current value is 4 or less, then it is okay. For all digits of 5 and above, decimal correction is needed. This can be done by adding 6 to the shifted value or by adding 3 to the current value. If we add 3 to all current values and check if they are greater than 7, all number satisfying this condition will need decimal correction and we will just keep that added number, otherwise we fall back to the original number.

This decimal correction process applies also to the most significant digit, except we use \$30 instead of 3.

bindec	; entry ; exit:	t binary to BCD conversi : 32 bit binary number in 10 digit BCD number in 3 ithm= shift the bits of bin decimal correct or count,#32	\$10-13 \$14-18 hary number into the BCD number and
billace	mov	fsr,#bcd_number	; points to the BCD result
clr_bcd	clr snb jmp inc jmp	ind fsr.3 shift_both fsr clr_bcd	; clear BCD number ; reached \$18? ; yes, begin algorithm ; no, continue on next byte ; loop to clear
shift_both	mov clc	fsr,#bin_number	; points to the binary number input ; clear carry, prepare for shifting

shift_loop	rl snb	ind fsr.3		; shift the number left ; reached \$18? (finish shifting both ; numbers)
	jmp inc jmp	check_adj fsr shift_loop		; yes, check if end of everything ; no, next byte ; not yet
check_adj	decsz jmp ret	count bcd_adj		; end of 32 bit operation? ; no, do bcd adj
bcd_adj	mov	fsr,#bcd_numb	er	; points to first byte of the BCD result
bcd_adj_loop	call snb jmp inc jmp	digit_adj fsr.3 shift_both fsr bcd_adj_loop		; decimal adjust ; reached last byte? ; yes, go to shift both number left again ; no, next byte ; looping for decimal adjust
digit_adj	mov add mov snb mov ; now f mov add mov snb mov	der LSD first w,#3 w,ind temp,w temp.3 ind,w or the MSD w,#\$30 w,ind temp,w temp.7 ind,w	; which i ; > 7? if ; yes, de	ecome 6 on next shift is the decimal correct factor to be added bit 3 not set, then must be <=7, no adj. ecimal adjust needed, so store it ; 3 for MSD is \$30 ; add for testing ; > 7? ; yes, store it
				•

4.0 BCD to binary conversion

Input from keyboards can be easily rendered into BCD form. To let the CPU process the number effectively, however, binary representation is more desirable.

In this section we will discuss how the BCD to binary conversion process is implemented. It is basically a reversal of the binary to BCD conversion process: we shift the BCD number to the right and let the least significant bit be shifted into a binary result. The original BCD number is then continuously decimally corrected to maintain the BCD format.

In the following code segment, we have implemented a 10 digit BCD number to 32 bit binary number conversion routine. With the RR instruction of the SX, the shift operation of both numbers together can be very efficiently implemented.

Decimal correction is done again differently here since we are shifting right instead of shifting left.

Current value	binary	Shifted value in binary	Shifted value in hex	What the shifted value should be in BCD
0	0000	0000	0	0
2	0010	0001	1	1
4	0100	0010	2	2
6	0110	0011	3	3
8	1000	0100	4	4
10	10000	1000	8	5
12	10010	1001	9	6
14	10100	1010	A	7
16	10110	1011	В	8
18	11000	1100	С	9

To derive the algorithm, let's look at the following table:

As we can see, whenever the shifted value has a 1 on bit 3, the result should be subtracted with 3 to make it correct. And this is the algorithm that we have adopted in the following code: shift right both numbers and decimally adjust the BCD number along the way. Note that for the most significant digit in each BCD number, we subtract \$30 instead of 3 to account for its position.

	 ; 10 digit BCD to 32 bit binary conversion ; entry: 10 digit BCD number in \$14-18 ; exit: 32 bit binary number in \$10-13 ; algorithm= shift the bits of BCD number into the binary number and decimal ; correct on the way 		
decbin	mov	count,#32	; 32 bit number
	mov	fsr,#bin_number	; points to the binary result
clr_bin	clr	ind	; clear binary number
	inc	fsr	; no, continue on next byte
	snb	fsr.2	; reached \$13? (then fsr will be \$14 here)
	jmp	shift_b	; yes, begin algorithm
	jmp	clr_bin	; loop to clear
shift_b	mov clc	fsr,#bcd_number+4	; points to the last BCD number ; clear carry, prepare for shifting right
shft_loop	rr	ind	; shift the number right
	dec	fsr	; reached \$10? (finish shifting both numbers)
	sb	fsr.4	; then fsr will be \$0f
	jmp	chk_adj	; yes, check if end of everything
	jmp	shft_loop	; not yet
chk_adj	decsz jmp ret	count bd_adj	; end of 32 bit operation? ; no, do bcd adj
bd_adj	mov	fsr,#bcd_number	; points to first byte of the BCD result
bd_adj_loop	call	dgt_adj	; decimal adjust
	snb	fsr.3	; reached last byte?

	jmpshift_b; yes, go to shift both number right againincfsr; no, next bytejmpbd_adj_loop; looping for decimal adjust	
	; prepare for next shift right ; $0000 \rightarrow 00000 \rightarrow 0$; $0010 \rightarrow 0001 2 \rightarrow 1$; $0100 \rightarrow 0010 4 \rightarrow 2$; $0110 \rightarrow 0011 6 \rightarrow 3$; $1000 \rightarrow 0100 8 \rightarrow 4$	
	; 1 0000> 1000 10>8 !! it should be 5, so -3	
	; 1 0010> 1001 12>9 !! it should be 6, so -3 ; in general when the highest bit in a nibble is 1, it should be subtracted with 3	
dgt_adj	; consider LSD firstsbind.3jmpck_msdstc; check highest bit in LSD, =1?; no, check MSD; prepare for subtraction, no borrow	
	sub ind,#3 ; yes, adjust	
ck_msd	; now for the MSD sb ind.7 ; highest bit in MSD, =1? ret ; no	
	; yes, do correction stc ; no borrow sub ind,#\$30 ; this is a 2 word instruction, and cannot be sk ret	ipped

5.0 Multiplication

The need for multiplication permeates through the use of microcontrollers. Here we will consider both 8 bit by 8 bit and 16 bit by 16 bit multiplications. As we can see, the basic algorithms are all the same regardless of the number of bits involved.

Let's first discuss how the multiplier, multiplicand, and the result are generally organized. Multiplicand

Upper product	Multiplier (lower product)
Opper product	Multiplier (lower product)

The lower part of the result are initially occupied by the multiplier and the upper part is cleared to zero.

To summarize, the following steps are needed to do a multiplication by software:

1. Initialize multiplier, multiplicand from calling program;

2. clear the upper product to zero;

3. shift right the whole product to the right;

4. if carry is 1, i.e., the lsb of the multiplier is one, then add the multiplicand to the upper product;

5. repeat step 3 and 4 until all bits of the multiplier has been shifted out

This algorithm is amazingly elegant as we can see in the next program segment.

As implemented for 8 bit by 8 bit multiplication, this routine requires only 2 bytes of RAM provided the multiplicand is pre-loaded into the W, working register.

	; 8 bit x 8 bit multiplication (RAM efficient, 2 bytes only) ; entry: multiplicand in W, multiplier at 09 ; exit : product at \$0a,09				
				; cycle	S
mul88	mov	upper_prdt,w		;1	store W
	mov	count,#9		;2	set number of times to shift
	mov	w,upper_prdt		;1	restore W (multiplicand)
	clr	upper_prdt		; 1	clear upper product
	clc			; 1	clear carry
				; the fo	bllowing are executed [count] times
m88loop	rr	upper_prdt		; 1	rotate right the whole product
-	rr	multiplier		; 1	check lsb
	snc	·		; 1	skip addition if no carry
	add	upper_prdt,w		; 1	add multiplicand to upper product
no_add	decsz	count		; 1/2	loop 9 times to get proper product
	jmp	m88loop		; 3	jmp to rotate the next half of product
	ret			; 3	done
			; one ti	me instr	ructions = 1+2+1+1+1+3= 9 cycles
					es= (1+1+1+1+1+3)9-3+2=71
			; total v	vorst ca	se cycles=80 cycles

A faster implementation can be obtained if we unroll the loop and repeat the code using a macro:

	; entry	B bit x 8 bit multiplicati : multiplicand in W, m product at \$0a,09				
rra	; macro to rotate product right and add MACRO					
na	-		. 1	ratata right the whole product		
	rr	upper_prdt	; 1	rotate right the whole product		
	rr	multiplier	; 1	check lsb		
	snc	-	; 1	skip addition if no carry		
	add	upper_prdt,w	; 1	add multiplicand to upper product		
	ENDM	•• -• •	, .			
		es				
fmul88	clr	upper_prdt	; 1	clear upper product		

clc	; 1 clear carry ; the following are executed [count] times
rra	; call the macro 9 times
rra	
ret	; 3 done ; one time instructions = 1+1+3= 5 cycles ; repetitive ones= (1+1+1+1)9=36 ; total worst case cycles=41 cycles

We have saved almost half of the time by using macros and eliminating the loop control. Notice that in both algorithms, 9 shifts are needed to obtain a correct result. The last shift is used to align the result properly.

The same algorithm has been implemented for 16 bit by 16 bit multiplication, which is included as follows:

	; 16 bit x 16 bit multiplication ; entry: multiplicand in \$09,08, multiplier at \$0b,\$0a ; exit : 32 bit product at \$0d,\$0c,\$b,\$a				
	; cycles				
mul1616			_		
	mov	count,#17	; 2	set number of times to shift	
	clr	upper_prdt	; 1	clear upper product	
	clr	upper_prdt+1	; 1	higher byte of the 16 bit upeper product	
	clc		; 1	clear carry	
; the following are exec			following are executed [count] times		
m1616loop	rr	upper_prdt+1	; 1	rotate right the whole product	
	rr	upper_prdt	; 1	lower byte of the 16 bit upper product	
	rr	mr16+1	; 1	high byte of the multiplier	
	rr	mr16	; 1	check lsb	
	SC		; 1	skip addition if no carry	
	jmp	no_add	; 3	no addition since lsb=0	
	clc		; 1	clear carry	
	add	upper_prdt,md16	; 1	add multiplicand to upper product	
	add	upper_prdt+1,md16+1		add the next 16 bit of multiplicand	
no_add	decsz	count	; 1/2	loop [count] times to get proper product	
_	jmp	m1616loop	; 3	jmp to rotate the next half of product	
	ret		; 3	done	
	; one t			time instructions = 8 cycles	
	; repetitive ones= 15*16+11+2=253				
; total worst case cycles=261 cycles					
Note that the only difference is the number of bits that we shift, and more bytes to					

Note that the only difference is the number of bits that we shift, and more bytes to add and rotate. Other than that, it is basically the same as a 8×8 multiplication. A fast version is also available but it is too lengthy to list here. Please see the program file for

details. A saving of 26% is achieved here by unrolling the loop and reduced the cycles to 193.

6.0 Division

Finally, we are going to tackle the most difficult arithmetic problem: that of divison. If the reader can recall how he or she was taught how to do division by long hand, then we are very close to understanding the algorithm.

In division by long hand, we examine the dividend digit by digit, and see if it is bigger than the divisor. If it is, then we subtract the divisor or the multiples of it from the dividend and write down that multiple as a digit in our quotient. This process is repeated until all digits of the dividend are exhausted.

This exact process is being implemented in the following code segment with one difference with our long hand division: we are dealing with binary numbers here. So we modify the algorithm as follows:

1. initialize the result and remainder register;

2. shift the dividend bit by bit into the remainder register (use as a placeholder here);

3. do a trial subtraction of the partial dividend in the remainder register and the divisor;

4. if the partial dividend is bigger than the divisor, then we subtract the divisor from it and record a 1 bit for the quotient

5. shift the quotient to left so that we can calculate the next bit, and repeat step 2 thru 4 till all bits of the dividend is exhausted.

	; 16 bit by 16 bit division (b/a) ; entry: 16 bit b, 16 bit a ; exit : result in b, remainder in remainder			
			; cycle	es
div1616	mov	count,#16	; 2	no. of time to shift
	mov	d,b	; 2	move b to make space
	mov	d+1,b+1	; 2	for result
	clr	b	; 1	clear the result fields
	clr	b+1	; 1	one more byte
	clr	rlo	; 1	clear remainder low byte
	clr	rhi	; 1	clear remainder high byte
			; subto	otal=10
divloop	clc		; 1	clear carry before shift
	rl	d	; 1	check the dividend
	rl	d+1	; 1	bit by bit
	rl	rlo	; 1	put it in the remainder for
	rl	rhi	; 1	trial subtraction
			; subto	otal=5
	stc		; 1	prepare for subtraction, no borrow
	mov	w,a+1	; 1	do trial subtraction
	mov	w,rhi-w	; 1	from MSB first
	SZ		; 1/2	if two MSB equal, need to check LSB
	jmp	chk_carry	; 3	not equal, check which one is bigger
			;	

	; if we are here, then z=1, so c must be 1 too, since there is no ; underflow, so we save a stc instruction				
	mov mov	w,a w,rlo-w	; 1 ; 1 ; subto	equal MSB, check LSB which one is bigger? tal=7	
chk_carry	sc jmp	shft_quot	; 1/2 ; 3	partial dividend >a? no, partial dividend < a, set a 0 into quotient	
	; if we are here, then c must be 1, again, we save another stc instruction				
			part. dividend > a, subtract a from it		
	sub	rlo,a	; 2	store part. dividend-a into a	
	sub	rhi,a+1	; 2	•	
	stc		; 1	shift a 1 into quotient	
			; subto	tal=7 worst case	
shft_quot	rl	b	; 1	store into result	
	rl	b+1	; 1	16 bit result, thus 2 rotates	
	decsz	count	; 1/2		
	jmp	divloop	; 3		
				tal=6, 4 on last count	
	ret		; 3		
			,	me instructions=13	
			; repet ; total=	itive ones=(19+6)*15+19+4=398 411	

The fast version of this division algorithm is implemented by unrolling the loop and repeat all the instructions inside it. It consumes 336 cycles and therefore saves 18% of time.

7.0 Conclusions

The SX instructions, namely, ADD (add), ADDB (add bit), SUB (subtract), SUBB (subtract bit), CLC (clear carry), STC (set carry), RL (rotate left 1 bit), RR (rotate right 1 bit), are very useful in implementing arithmetic routines. With careful planning and smart algorithm design, all normal arithmetic functions can be accomplished.

Modifications and further options

There exists a lot of literature on computer arithmetic and the implementations included in this application note is not the only way of doing it. It only serves as an example for the readers and help them to bring their product to the market faster by using existing routines.

To test the example programs, remember to set the equate options mentioned in the first sentence of the program listing properly (for example, to use BCD routines, set **bcd_test equ 1** and reset all other options to 0). This will enable you to include only the code you need in a program.